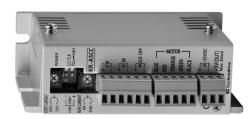
Technodrive

Motor Driver (5-phase Stepper Motor Driver) KR-A5CC





Thank you for choosing our Technodrive product. Please read the following safety considerations before use.

■ Safety Considerations

%Please observe all safety considerations for safe and proper product operation to avoid hazards.

Safety considerations are categorized as follows. **^Warning Failure to follow these instructions may result in serious injury or death.

⚠Caution Failure to follow these instructions may result in personal injury or product damage.

*The symbols used on the product and instruction manual represent the following ▲ symbol represents caution due to special circumstances in which hazards may occur.

∧ Warning

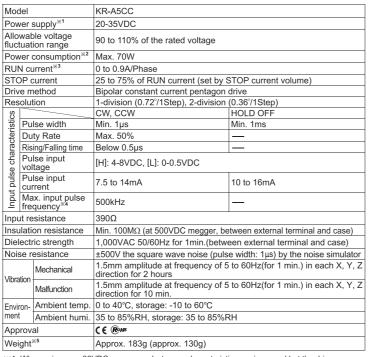
- 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, fire, or economic loss
- 2. Installation, connection, operation, maintenance, and inspection should be handled by
- Failure to follow this instruction may result in fire, electric shock or personal injury 3. Use reinforced insulation DC power at primary and secondary part for DC type input product.
- Failure to follow this instruction may result in electric shock.

 4. Install the unit after considering counter plan against power failure.
- Failure to follow this instruction may result in personal injury or product damage by releasing holding torque of motor.
- 5. Do not use the unit where flammable or explosive gas, corrosive material, water, or
- combustible material may be present.
 Failure to follow this instruction may result in fire, electric shock or burn.
- 6. Do not disassemble or modify the unit. Please contact us if maintenance necessary.
- Failure to follow this instruction may result in fire, electric shock or product damage. 7. Do not insert any objects at the openings of the unit.
- Failure to follow this instruction may result in fire, electric shock, or personal injury

⚠ Caution

- 1. Use the unit within the rated specifications.
- Failure to follow this instruction may result in product damage, shorten the life cycle of the unit personal injury, or peripheral devices damage.
- 2. Do not put obstacles around the unit which may obstruct ventilation Failure to follow this instruction may result in product damage by overheat, or malfunction of peripheral devices.
- 3. When connecting the power input cables, use the unit within the rated power supply and AWG18 (0.75mm²) cables.
- Failure to follow this instruction may result in fire or electric shock.
- 4. Refer to the connection diagrams and check the connection correctly before supplying the
- Failure to follow this instruction may result in fire, electric shock or product damage.
- 5. Turn OFF the power when power is failed. Failure to follow this instruction may result in personal injury or product damage due to sudden
- movement when recover power failure.
- 6. Do not touch the unit during or after operation for a while. Failure to follow this instruction may result in burn due to high temperature of the surface.
- Emergency stop should be available during operation.
- Failure to follow this instruction may result in personal injury or product damage
- 8. Check the control input signal of the unit before supplying the power. Failure to follow this instruction may result in personal injury or product damage by unexpected
- 9. Do not turn on the HOLD OFF signal input while it is maintaining vertical position. Failure to follow this instruction may result in personal injury or product damage by releasing holding
- 10. Install safety device when it is required to remain the vertical position after turn off the
- Failure to follow this instruction may result in personal injury or product damage by releasing holding
- 11. Check HOLD OFF signal input is ON when moving the output axis (manual positioning etc)
- manually. Failure to follow this instruction may result in personal injury by unexpected signal input.
- 12. Stop the unit when mechanical problem occurs.
- Failure to follow this instruction may result in fire, or personal injury.
- 13. Do not touch terminals when testing insulation resistance or dielectric strength...
- Failure to follow this instruction may result in electric shock. 14. Do not use water or oil-based detergent when cleaning the unit. Use dry cloth to clean the
- Failure to follow this instruction may result in electric shock or fire
- 15. When disposing the unit, please categorize it as industrial waste
- The above specifications are subject to change and some models may be discontinued with-

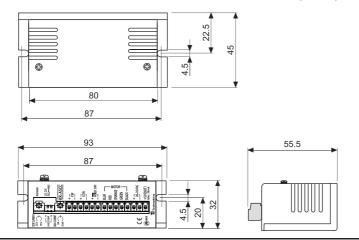
Specifications



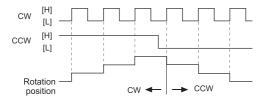
- X1: When using over 30VDC power supply, torque characteristics are improved but the driver temperature raise. The unit should be installed at the well ventilation environment
- ×2: Based on ambient temperature 25°C, ambient humidity 55%, STOP current 75%
- *3: RUN current is varied by inputted RUN frequency, RUN current of max, moment is varied by loads.
- ×4: Max, input pulse frequency is varied by max, pull-out frequency and max, slewing frequency area
- %5: The weight includes packaging. The weight in parentheses is for unit only.
- Environment resistance is rated at no freezing or condensation

Dimensions

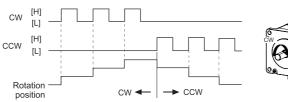
(unit: mm)



Time Chart

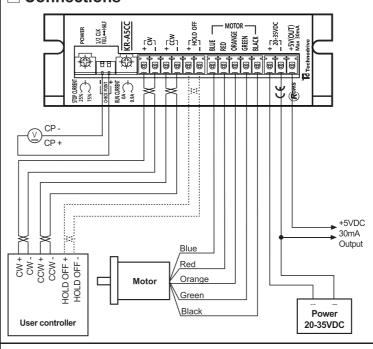


2-pulse input method



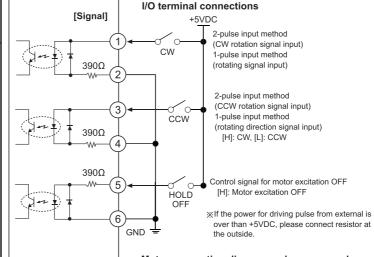
% Do not input CW, CCW signals at the same time in 2-pulse input type. It may not operate properly if another direction signal is inputted when one of CW or CCW is [H].

Connections

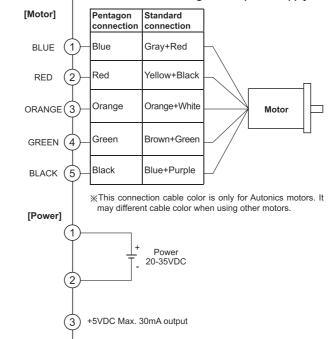


I/O Circuit And Connections

<KR-A5CC inner circuit>



Motor connection diagram and power supply



■ Function Selection DIP Switch

	ON 1 2	No.	Nameplate	Function	Switch position	
					ON	OFF(Factory default)
		1	1/2 CLK	Pulse input method	1-pulse input method	2-pulse input method
		2	FULL↔HALF	Select resolution	1-division(0.72°)	2-division(0.36°)

*Changing resolution is available only when stepper motor stops. If changing the resolution during operation, the motor may be out of phase

Setting RUN Current

RUN CURRENT



- RUN current is phase current provided for motor when the
- When RUN current is increased. RUN torque of the motor. is also increased. Set the RUN current within the range of motor's phase current according to its load.

*When RUN current is set too high, the heat is severe.

When RUN current is too low, RUN torque is decreased. XChange RUN current only when the motor stops.

■ Setting STOP Current

STOP CURRENT



25%

- STOP current is phase current provided for motor when · Adjuster of STOP current is percentage (%) ratio of the set
- RÚN current.
- E.g.) Set RUN current as 1.0A and set adjuster of STOP current as 50%. STOP current is set as 0.5A/Phase.

*When STOP current is set too high, the heat is severe.

When STOP current is too low, STOP torque is decreased.

XChange STOP current only when the motor stops.

HOLD OFF Function

- This signal is for rotating motor's axis using external force or used for manual
- When hold off signal maintains over 1ms as [H], motor excitation is released. • When hold off signal maintains over 1ms as [L], motor excitation is in a normal
- *Must stop the motor for using this function.
- ※Refer to the I/O Circuit And Connections.

Caution During Use 1 For signal input

①Do not input CW, CCW signal at the same time in 2-pulse input type. It may not operate properly if another direction signal is inputted when one of CW or CCW is

@When the power for pulse operation is exceeded +5VDC, please connect resistor at the outside.

2. For supplying power

①Use the power enough to supply RUN current when turn on the power.

2) The current value indicated on power supply is the max. input of driver.

3 Check the polarity of power before operating the unit.

For cable connection

①Use twisted pair (over 0.2mm²) for the signal cable which should be shorter than

②Use electric wire of AWG 18 (0.75mm²) for motor (for extending) and power connection.

4. For installation

1) The unit must be installed with heat protection. Follow the below 2, 3 ②In order to increase heat protection efficiency of the driver, must install the heat

sink close to metal panel and keep it well-ventilated

③Excessive heat generation may occur on driver. Keep the heat sink under 80°C when installing the unit. (at over 80°C, forcible cooling shall be required.)

5. This product may be used in the following environments.

1 It shall be used indoor ③ Pollution degree 2

② Altitude up to 2000m Installation category II

Failure to follow these instructions may result in product malfunction.



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